

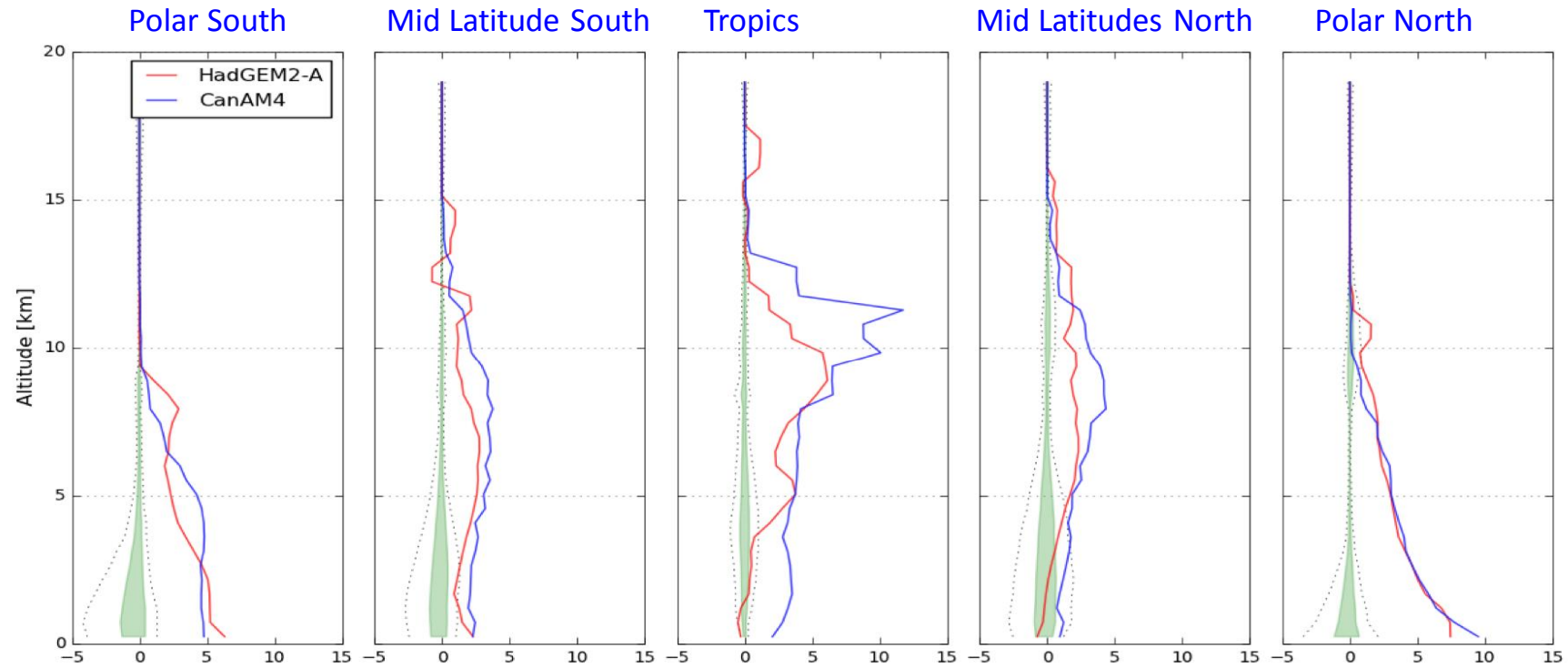
# Atmosphere Opacity observed by CALIPSO- link with cloud LW feedback

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# Background

The cloud vertical distribution is more sensitive to a forced climate warming than vertically integrated variables



Predicted forced change in the Cloud fraction profile (%)  
(AMIP+4K/COSP/lidar – AMIP/COSP/lidar)

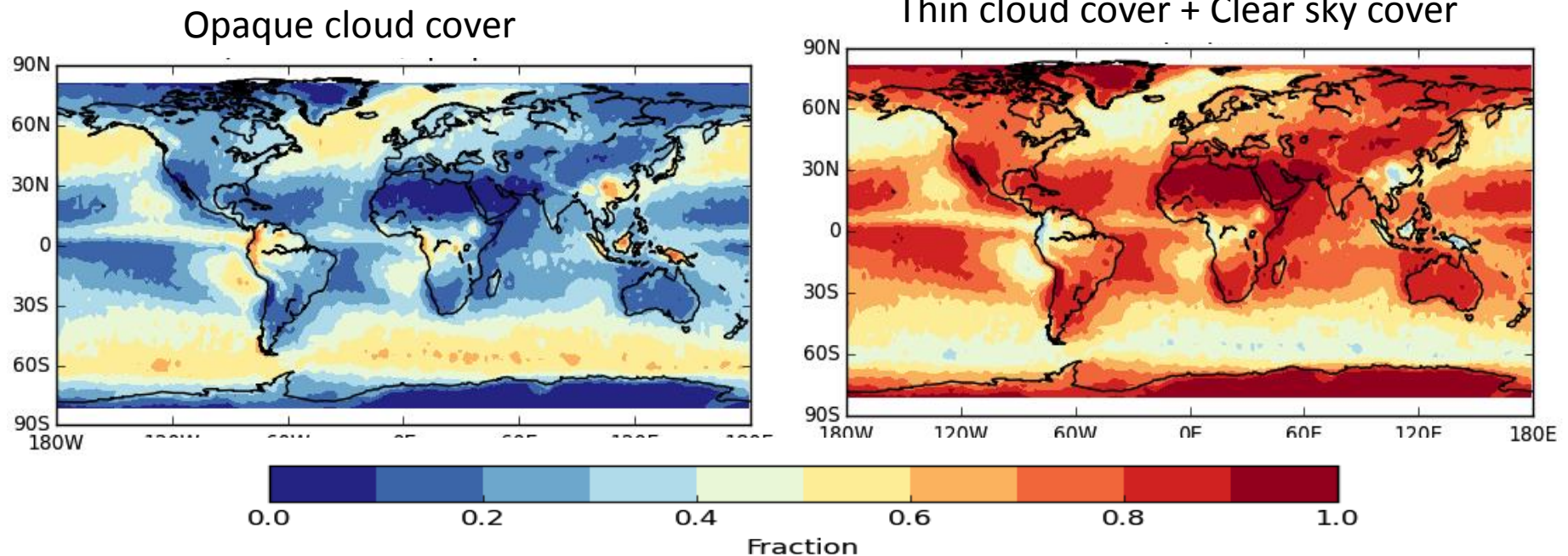
*Chepfer et al. 2014*

The expected forced change in the cloud vertical distribution (+4K) >> observed natural variability

# Background

Where the lidar is fully attenuated  
before reaching the surface  
about 30 %

Where the lidar sounds entirely the  
atmosphere down to the surface  
about 70%



Guzman et al, submitted

Consistent with Kato et al.

Consistent with M. Vaughan inputs

Calipso sounds entirely the atmosphere from the TOA to the surface in shallow cumulus and over continent most of the time  
Calipso is fully attenuated before to reach the surface in deep convective clouds and in the mid-latitude storms

# Background

Opaque Cloud Cover  
+  
Thin cloud Cover  
+  
Clear sky cover  
=  
100%

# Deep convective Tropical opaque clouds ( $\omega_{500} < 0$ )

Expected Cloud Feedback mechanism :

**Deep convective clouds are expected to rise up as surface temperature increases =>  
Positive LW cloud feedback, ... how much ?**

Hartmann et al. 2002

Zelinka et al. 2012

Wang et al. 2002

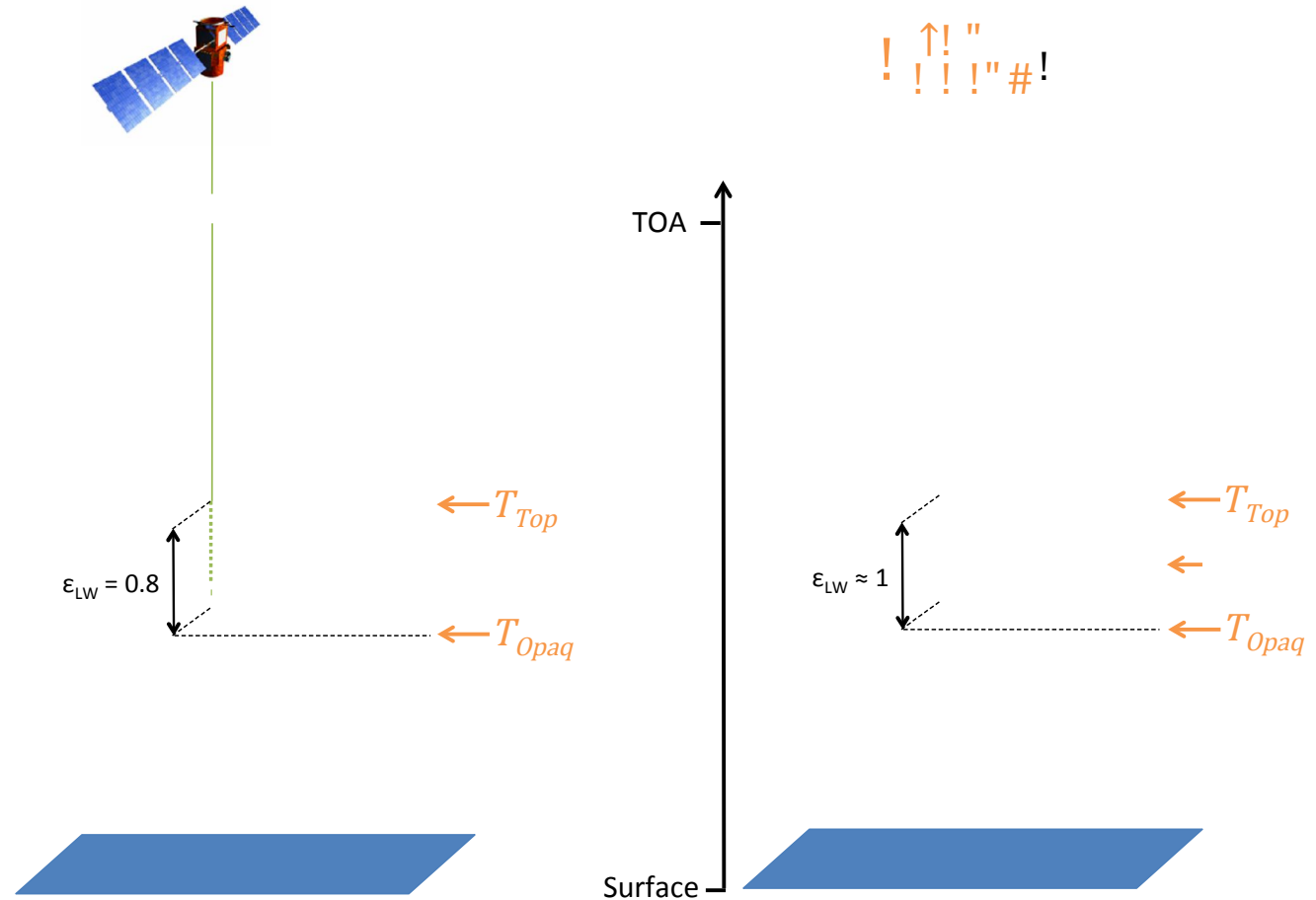
O'Gorman et al. 2013

Chepfer et al. 2014,

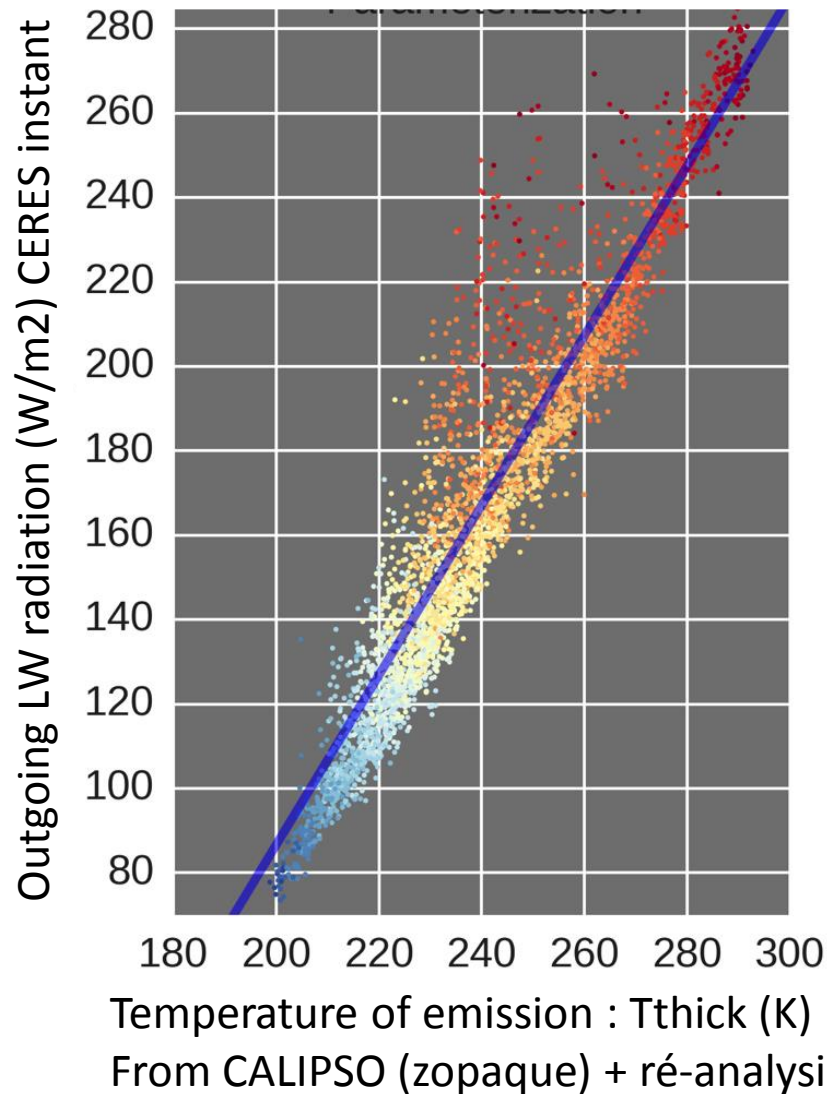
...

...

The altitude where the lidar is fully attenuated (in opaque cloud) drives LW outgoing rad: a direct precise stable measurement



# The altitude where the lidar is fully attenuated (in opaque cloud) drives LW outgoing rad: a direct precise stable measurement

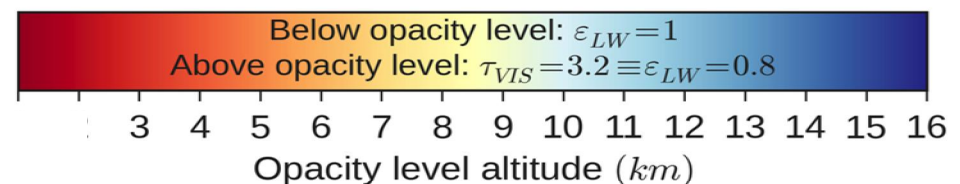


Dots = Observations in single columns/profiles where the lidar is fully attenuated

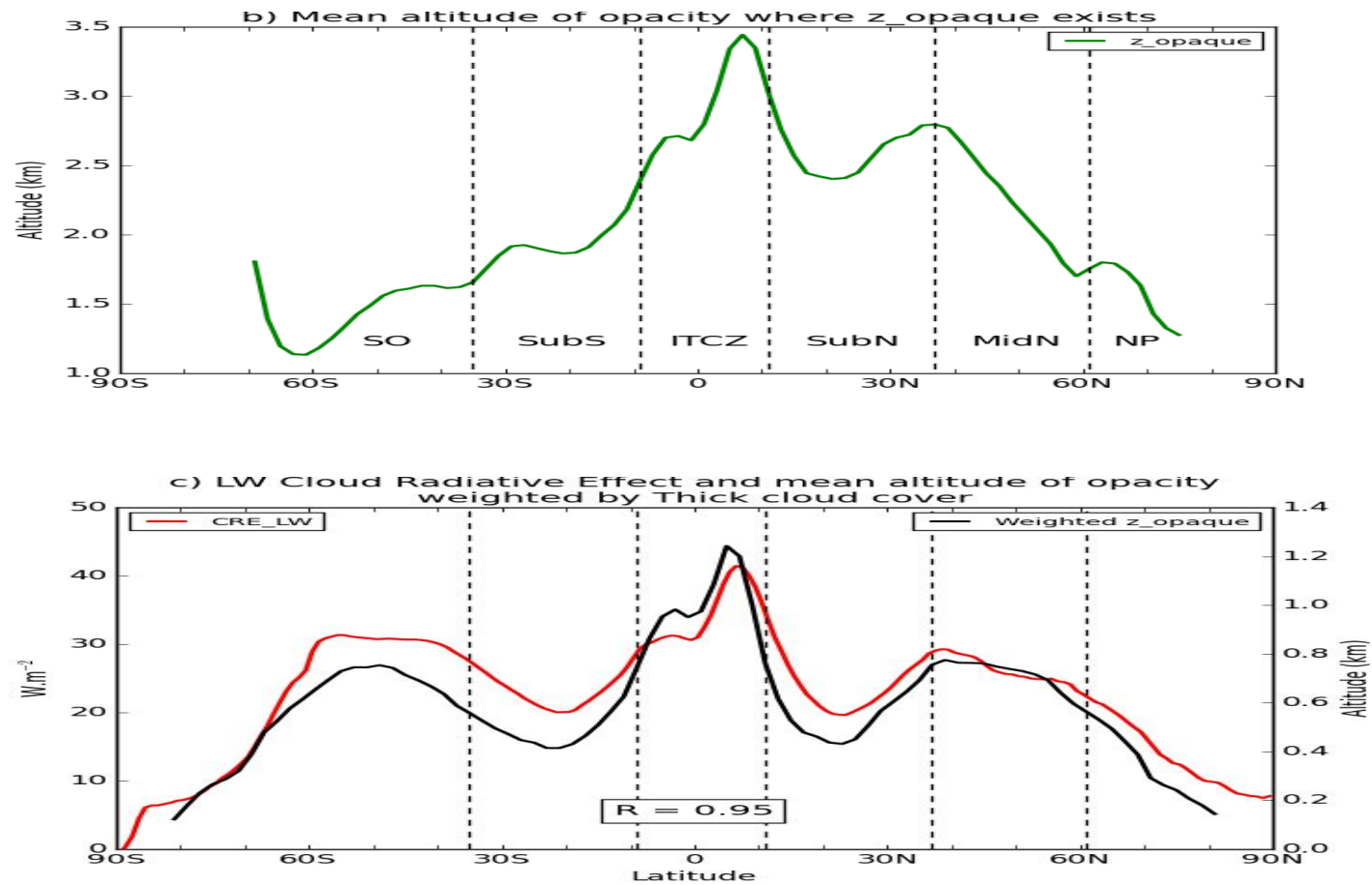
Blue line= theoretical direct radiative transfer computations, independent of observations

Slope = 2.0 W/m<sup>2</sup>/K ,  
consistent with Wang et al. 2002

Sherwood et al, 2004, Garnier et al. 2015



# Observations: Calipso opaque cover, altitude of opacity .vs. LW CRE



Guzman et al.,  
submitted



## Questions explored in this study

- Which record length is required to detect a cloud LW feedback signature = when does the forced cloud change goes out of the natural variability?
- How gaps or shifts in calibration between successive lidar missions impact the required record length ?

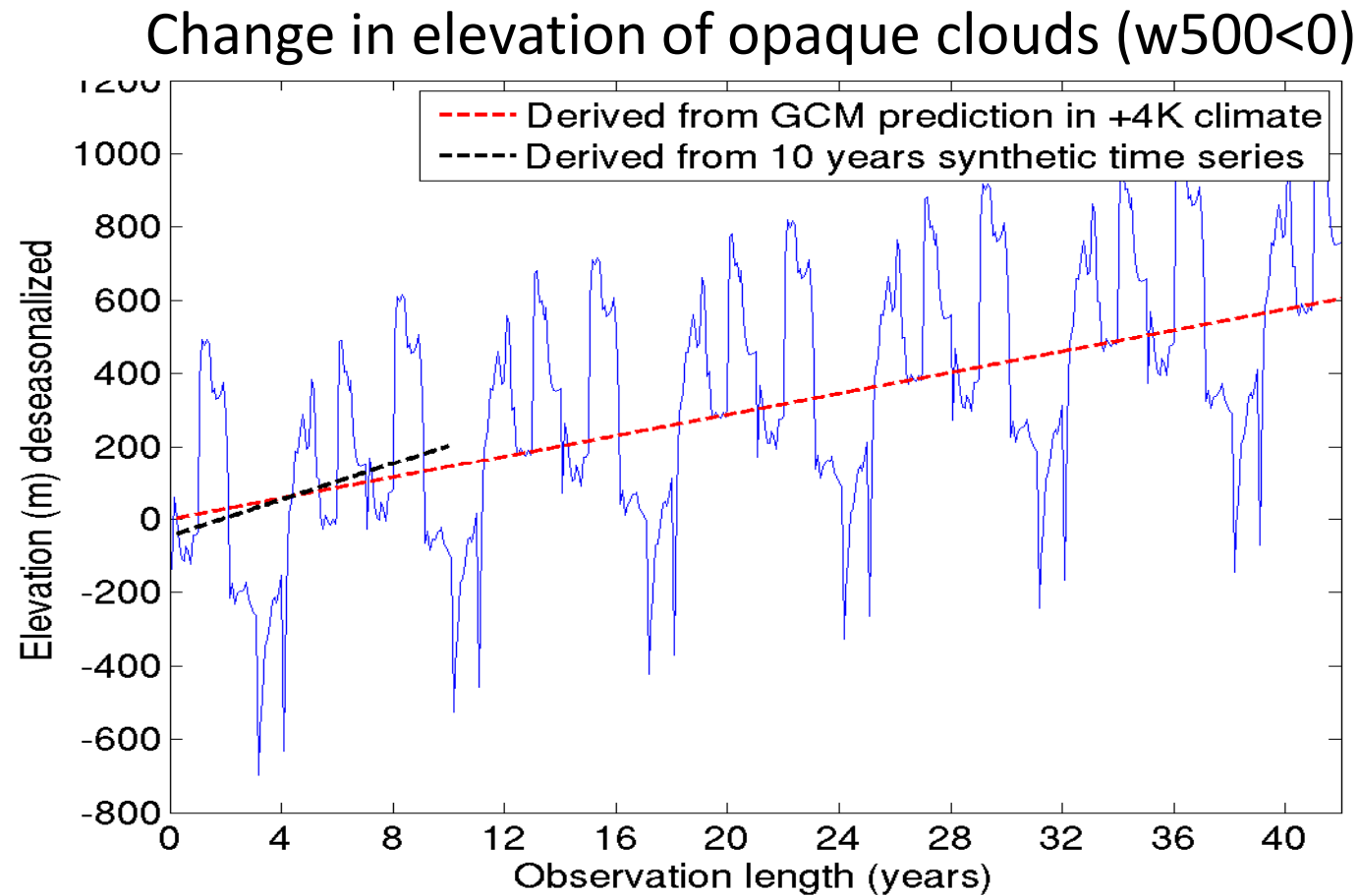
2) Built synthetic lidar time series constrained by the inter-annual variability from the actual Calipso record, and by the expected forced change predicted by AMIP+4K (assumed in 100 yrs) and AMIP as seen from a lidar in space (COSMO/lidar).

Method adapted from Loeb et al. 2009

3) Estimate the length of the lidar record required to provide an observational constraint on cloud feedbacks: when the forced signal goes out of the noise from natural variability

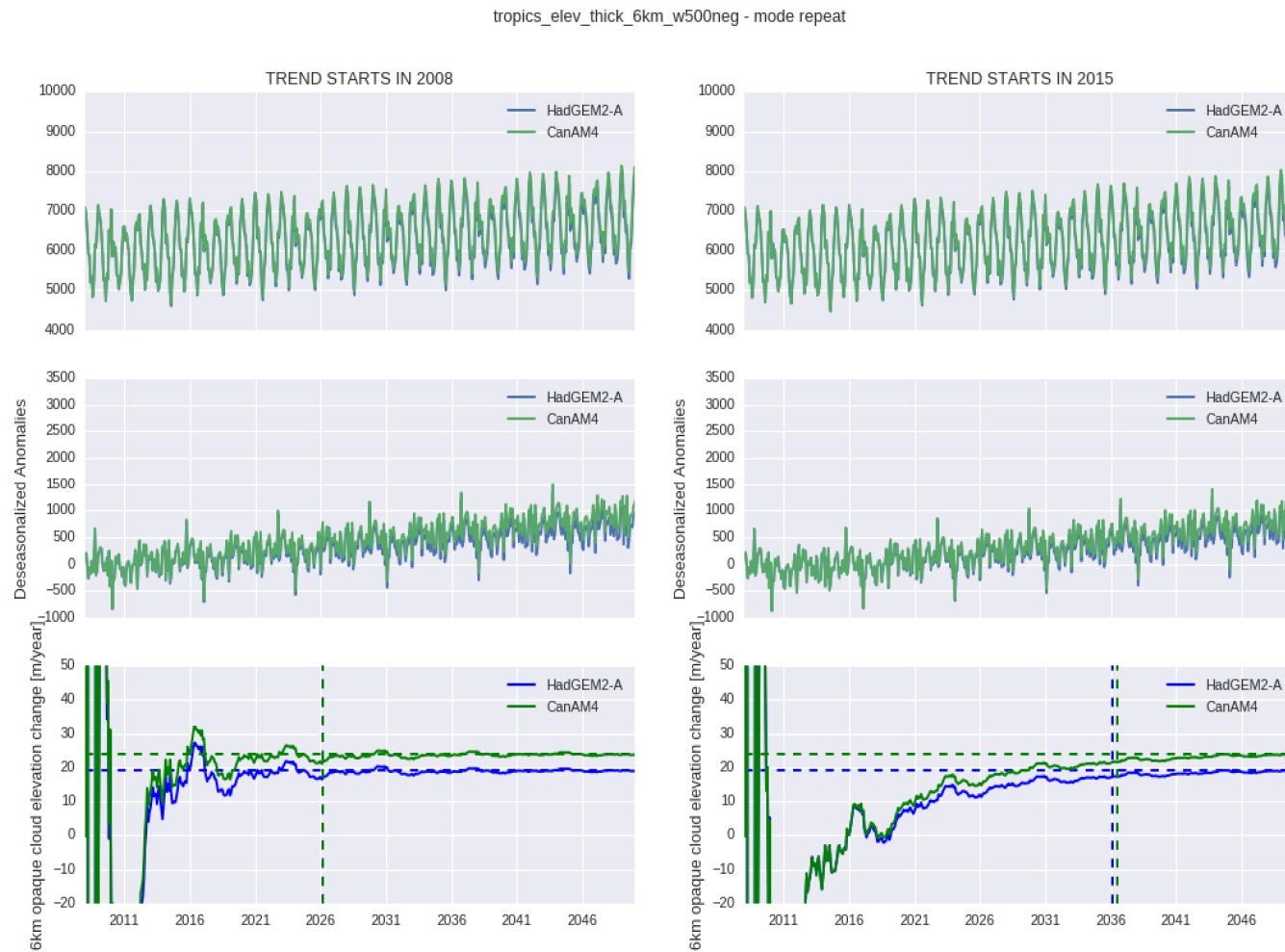
4) Estimate the impact of gaps and inter-calibration bias between lidar missions

# About the detectability of a forced opaque cloud elevation change in the tropical deep convection using lidars



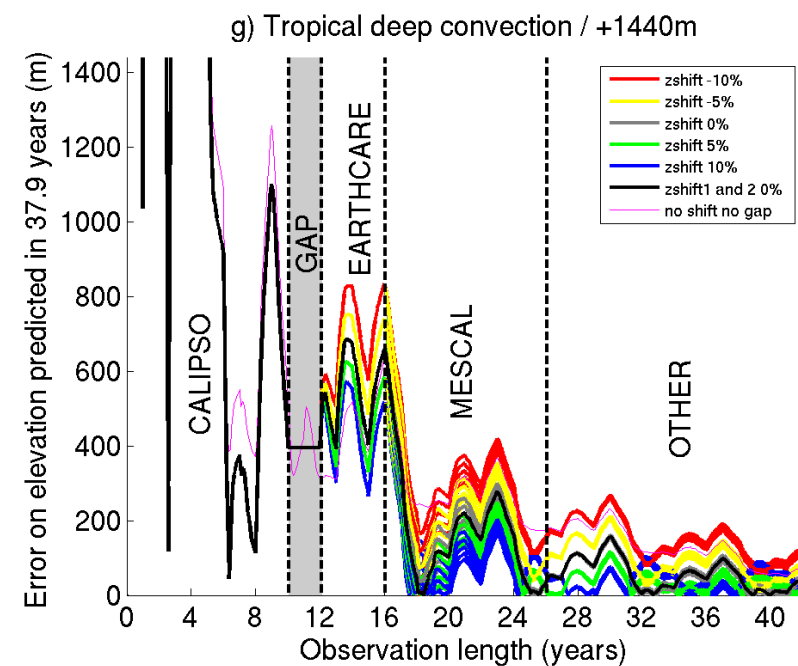
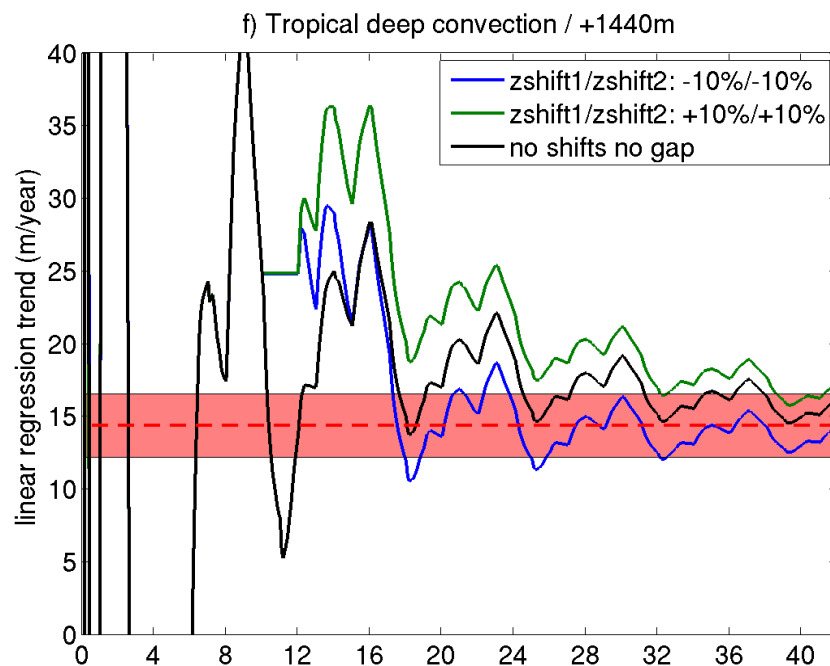
# When no shift, no gap between successive lidar missions (ideal)

## Trend in elevation of opaque clouds



# About the detectability of a forced thick cloud elevation change in the tropical deep convection using lidars

When gaps and inter-calibration biases between successive lidar missions



# Concluding remarks

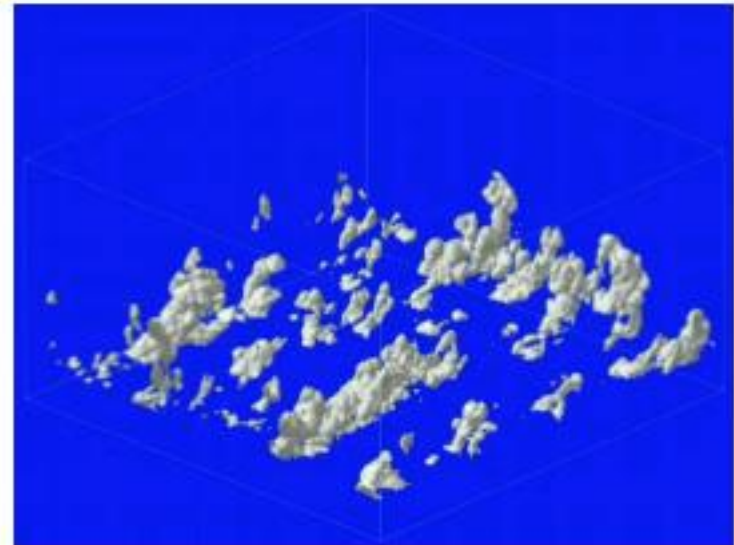
- “ The space active sensor (lidar,radar) are powerful process oriented tool for studying clouds: vertically precisely resolution , high horizontal resolution , accurate, stable in time,
- “ Potential to constrain high cloud tropical LW feedback mechanism,
- “ A third lidar/radar in space after Calipso and EarthCare would likely allow to observe the cloud response to greenhouse gazes forcing,
- “ Gaps between successive lidar/radar missions and inter calibration bias will delay the capability of a detection of the cloud response to greenhouse gazes forcing

What scale ? Ask Pier

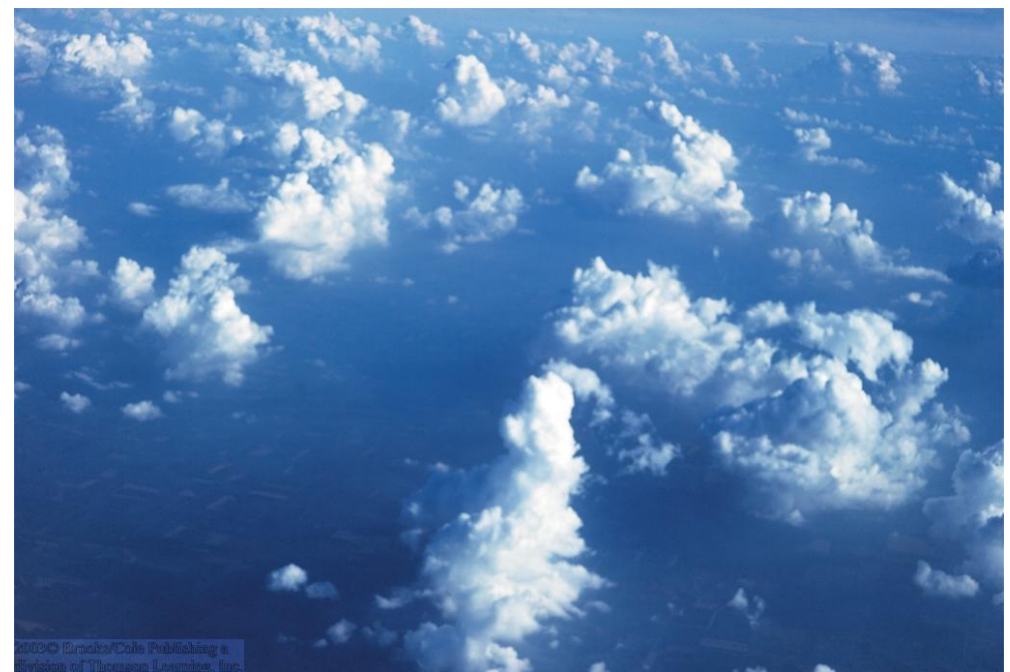


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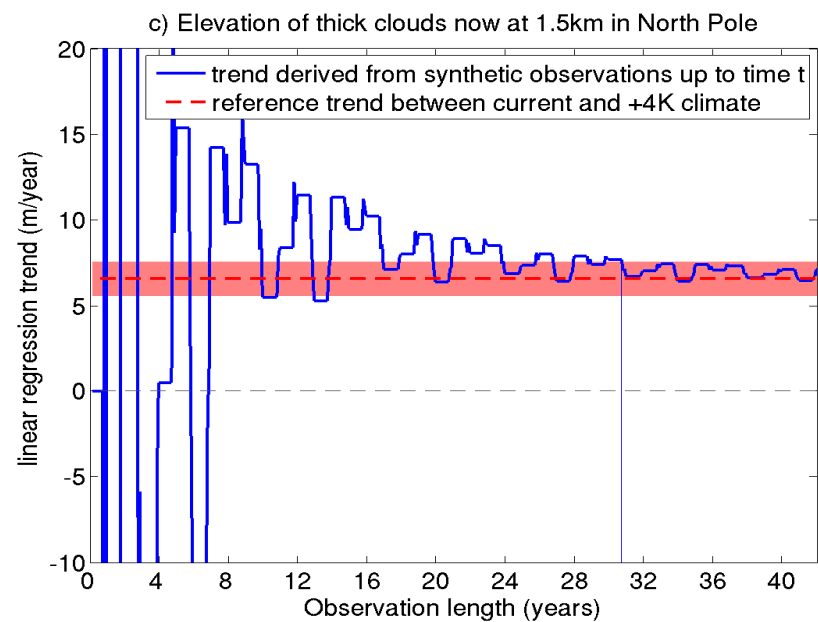
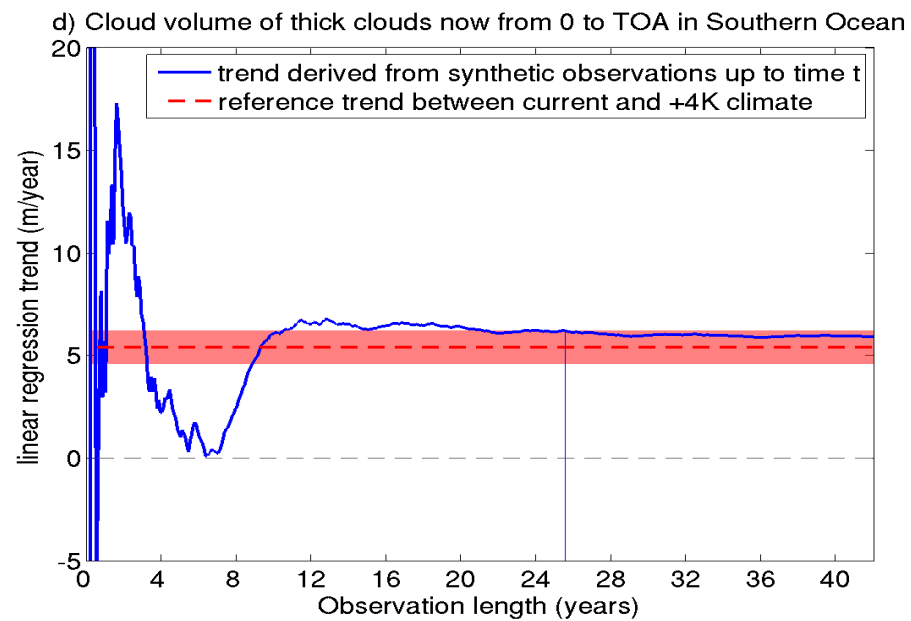
CMWF-08



2. **Cumulus.** Cumulus. Height (km): base=1, top=2, liquid composition, no precip, process: release of conditional instability.

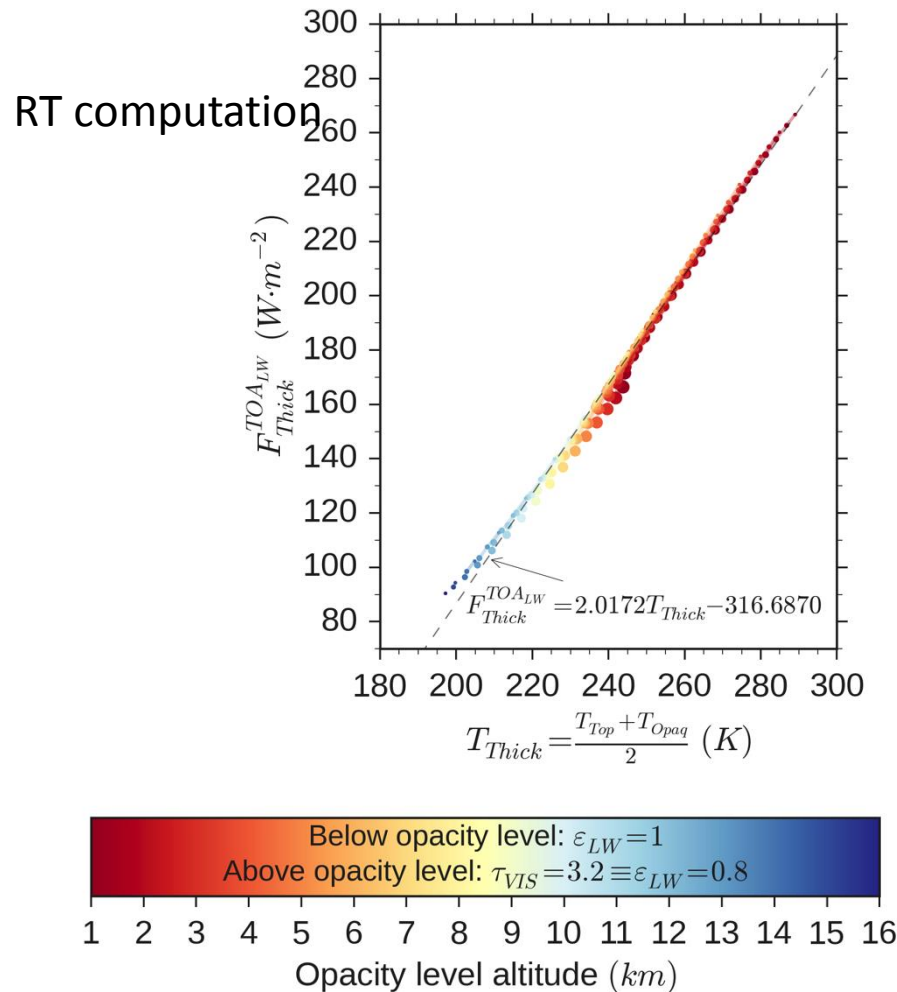


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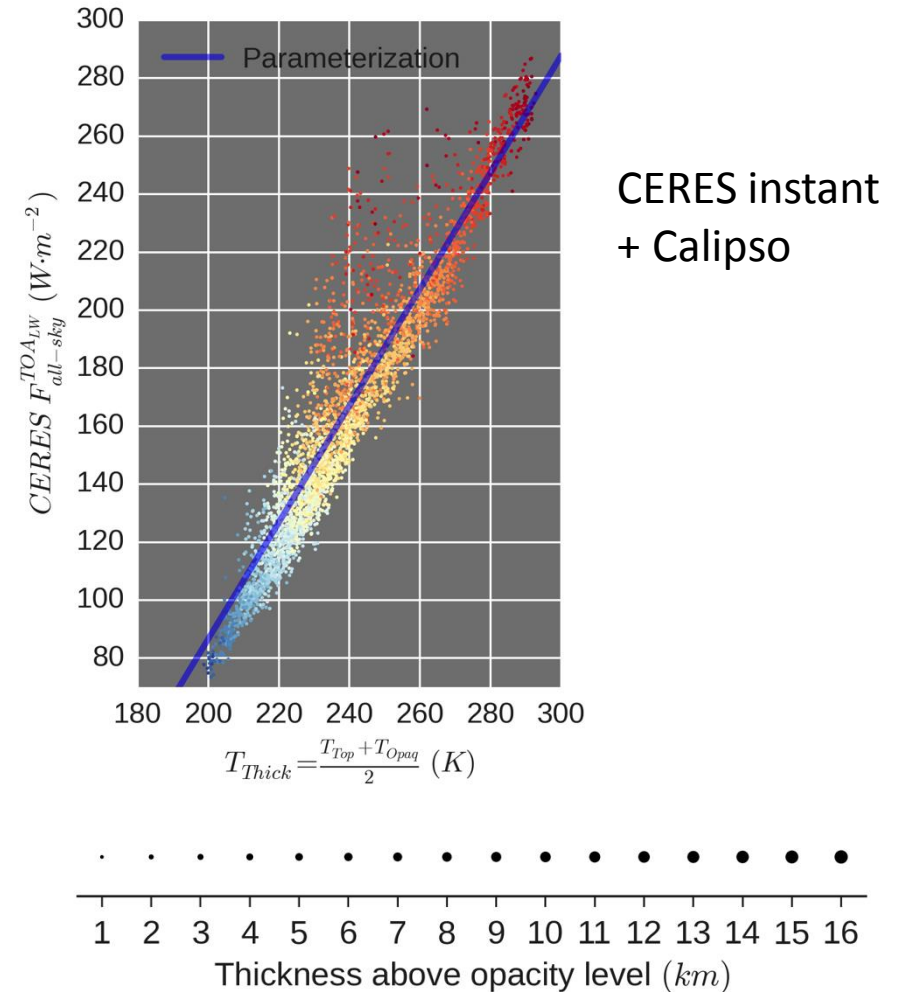




The altitude where the lidar is fully attenuated :  
a precise stable measurement for LW outgoing radiations



$k = 2.0 \text{ W} \cdot \text{m}^{-2}/\text{K}$  cohérent avec [Wang et al. 2002]



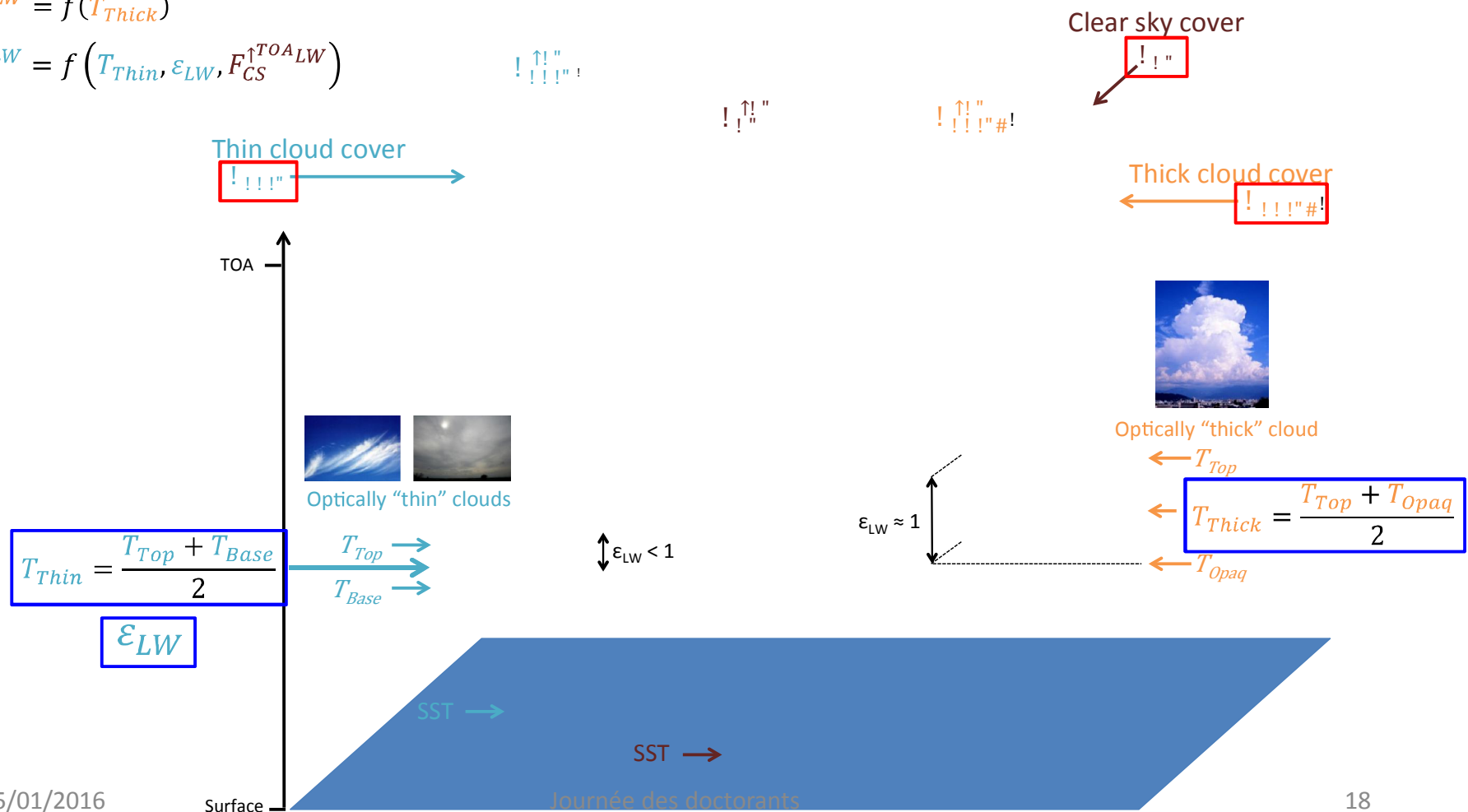
## Flux LW TOA total : regroupement des colonnes

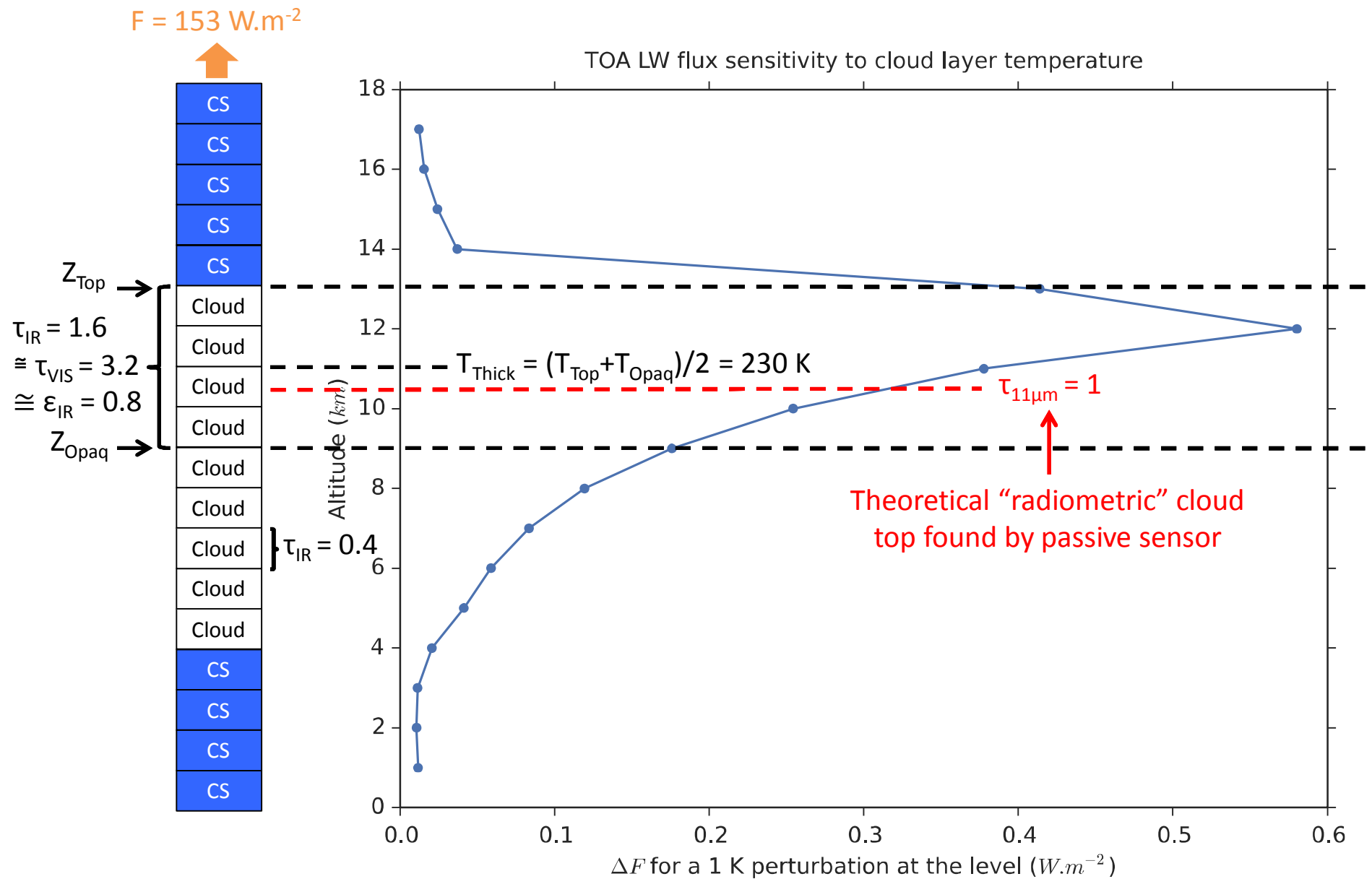
$$F_{Tot}^{\uparrow TOA LW} = C_{CS} F_{CS}^{\uparrow TOA LW} + C_{Thick} F_{Thick}^{\uparrow TOA LW} + C_{Thin} F_{Thin}^{\uparrow TOA LW}$$

$$C_{CS} + C_{Thick} + C_{Thin} = 1$$

$$F_{Thick}^{\uparrow TOA LW} = f(T_{Thick})$$

$$F_{Thin}^{\uparrow TOA LW} = f(T_{Thin}, \epsilon_{LW}, F_{CS}^{\uparrow TOA LW})$$





## 2 – L' algorithme OPAC

Quand l' atmosphère n' est pas sondée jusqu' à la surface

→ Détermination de l' altitude d' opacité  $z_{opaque}$

On se place dans le cadre de GOCCP pour déterminer  $z_{opaque}$  :

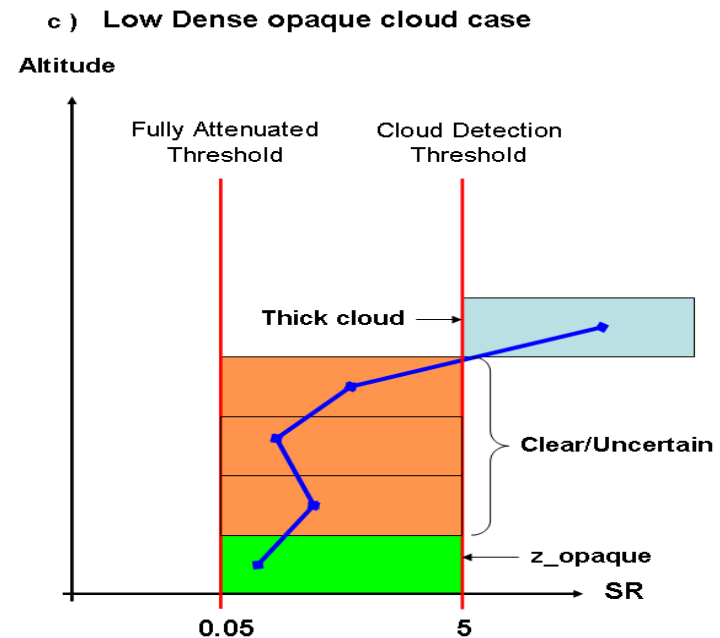
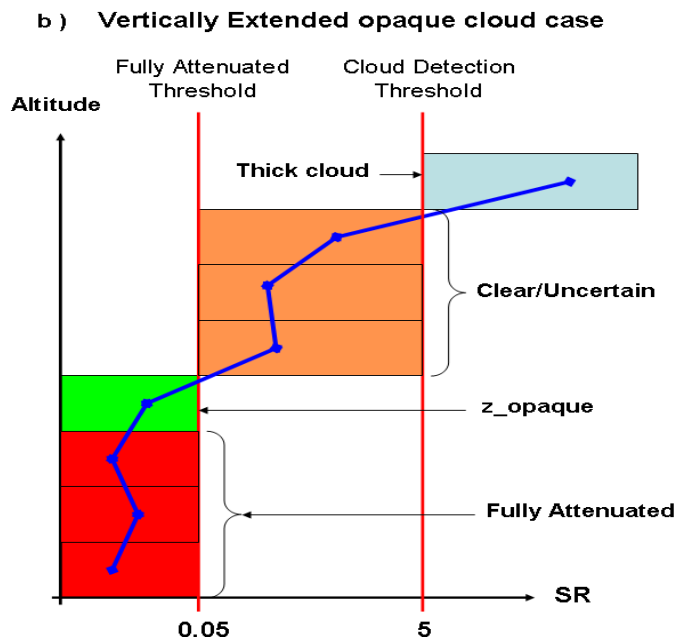
Couches atm. de 480 m,  $SR = ATB532 / ATB_{moléculaire}$ ,  $SR > 5 \rightarrow$  Cloud

- Deux cas de figure sous le nuage le plus bas détecté :

**$SR < 0.05$  existe**

ou

**$SR > 0.05$  seulement**



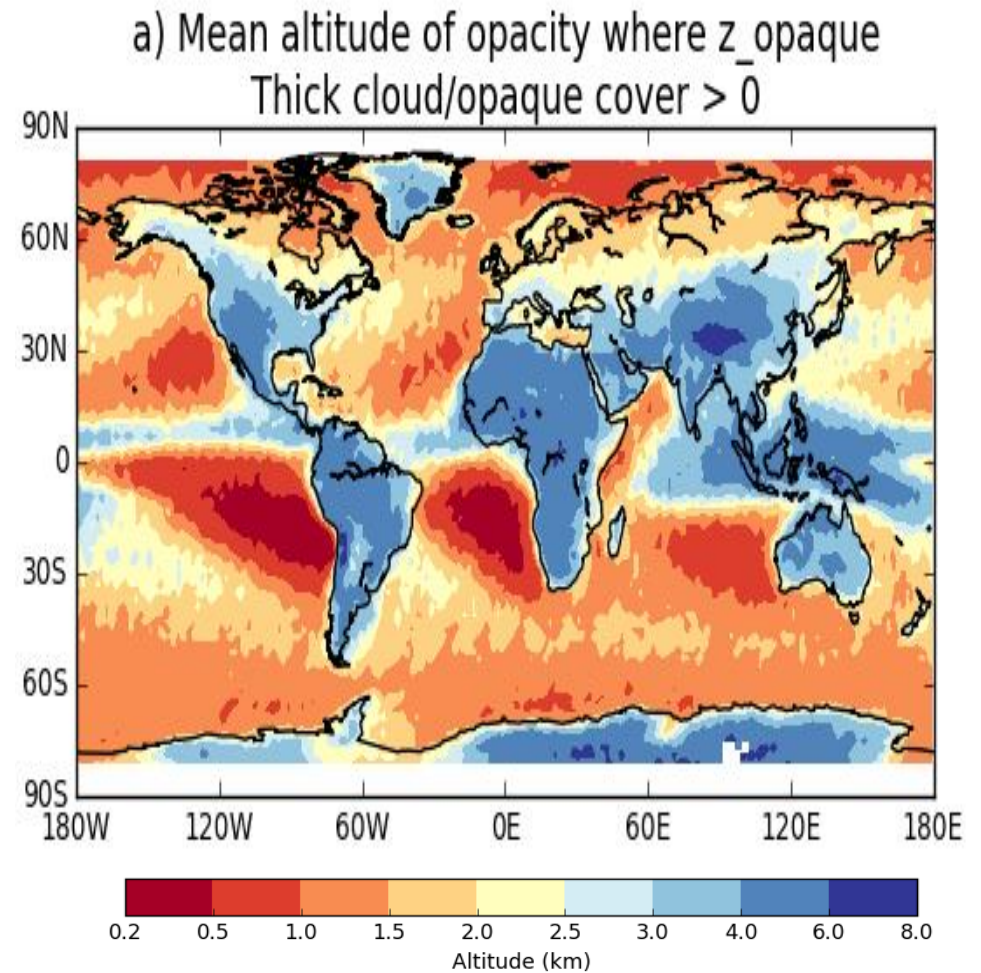
### 3 – Résultats (GOCCP-OPAC)

#### Level 3 : 2D Maps

Moyenne  $z_{\text{opaque}}$  calculée sur les profils opaques uniquement :

→ Structures de la circulation grande échelle apparaissent

→  $z_{\text{opaque}}$  élevé (4-6 km) dans des régions peu nuageuses (déserts)



### 3 – Résultats (GOCCP-OPAC)

#### Level 3 : 2D Maps

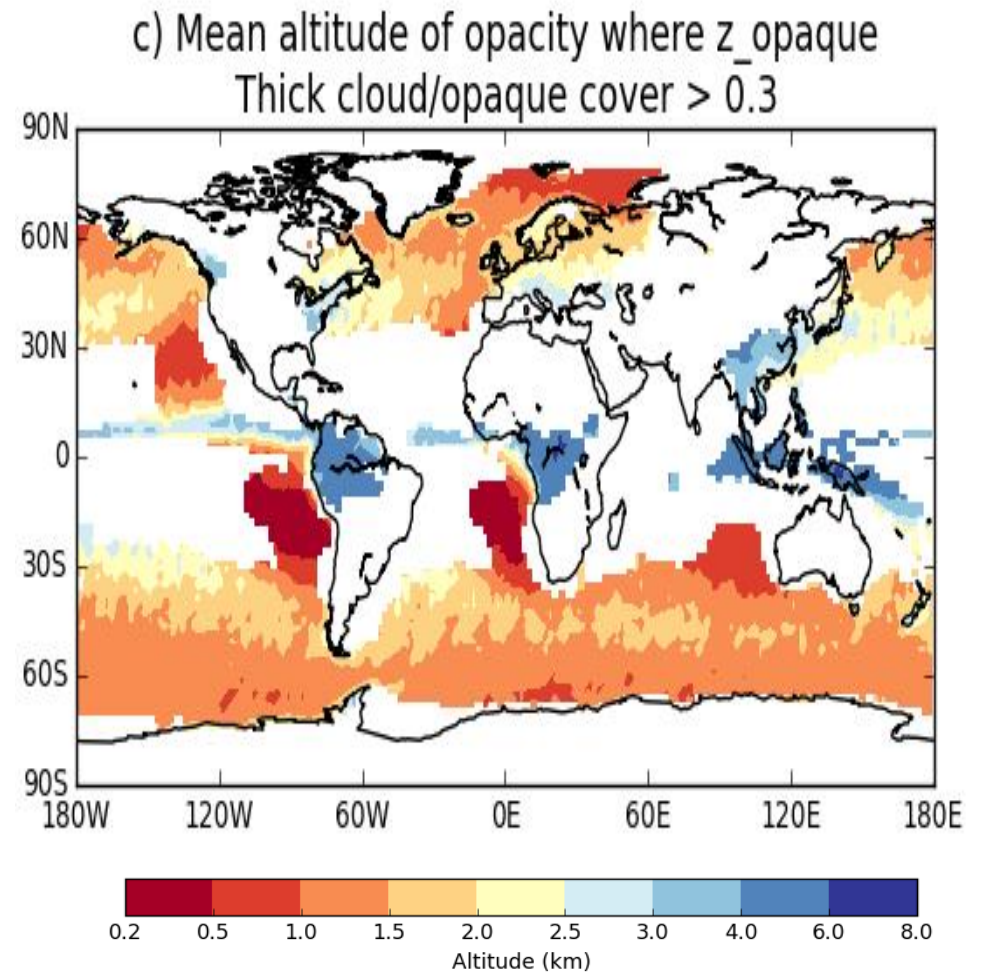
**Moyenne  $z_{\text{opaque}}$  pour régions où  
+30% des profils sont opaques**

→ zones de convection profonde  
( $z_{\text{opaque}} \sim 5$  km)

→ stratocumulus ( $z_{\text{opaque}} < 1$  km)

→ Southern Ocean ( $\sim 1,5$  km)

→ Storm track HN (1-2 km)



# Subsidence Tropical clouds ( $w_{500} > 0$ ) between 0 and 4 km of altitude

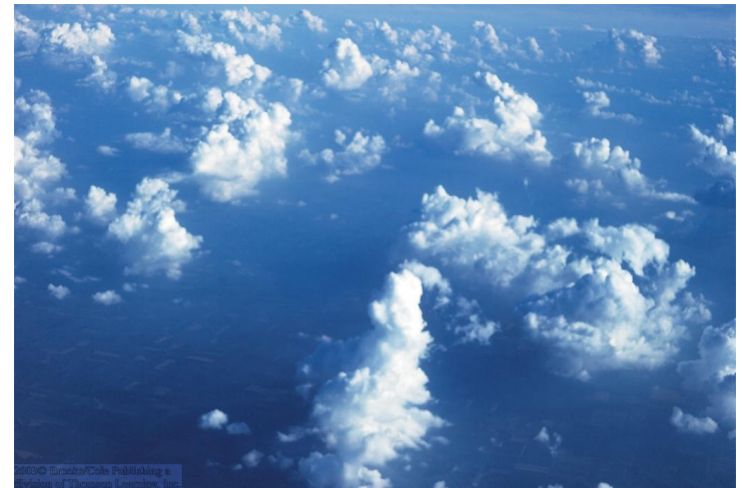
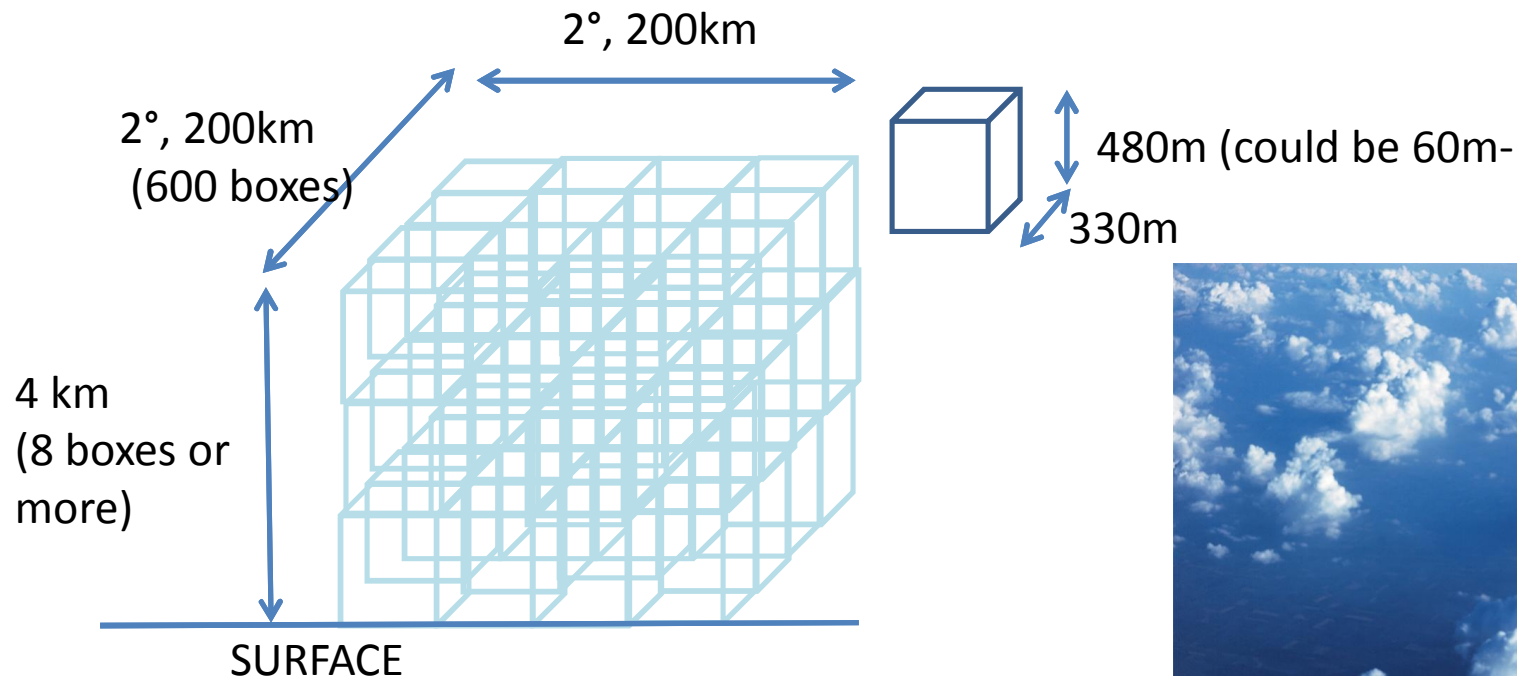
where Calipso sounds most of the time entirely the atmosphere from the TOA to the surface

SW cloud feedback  
Bony et al.  
Qu et al., ...



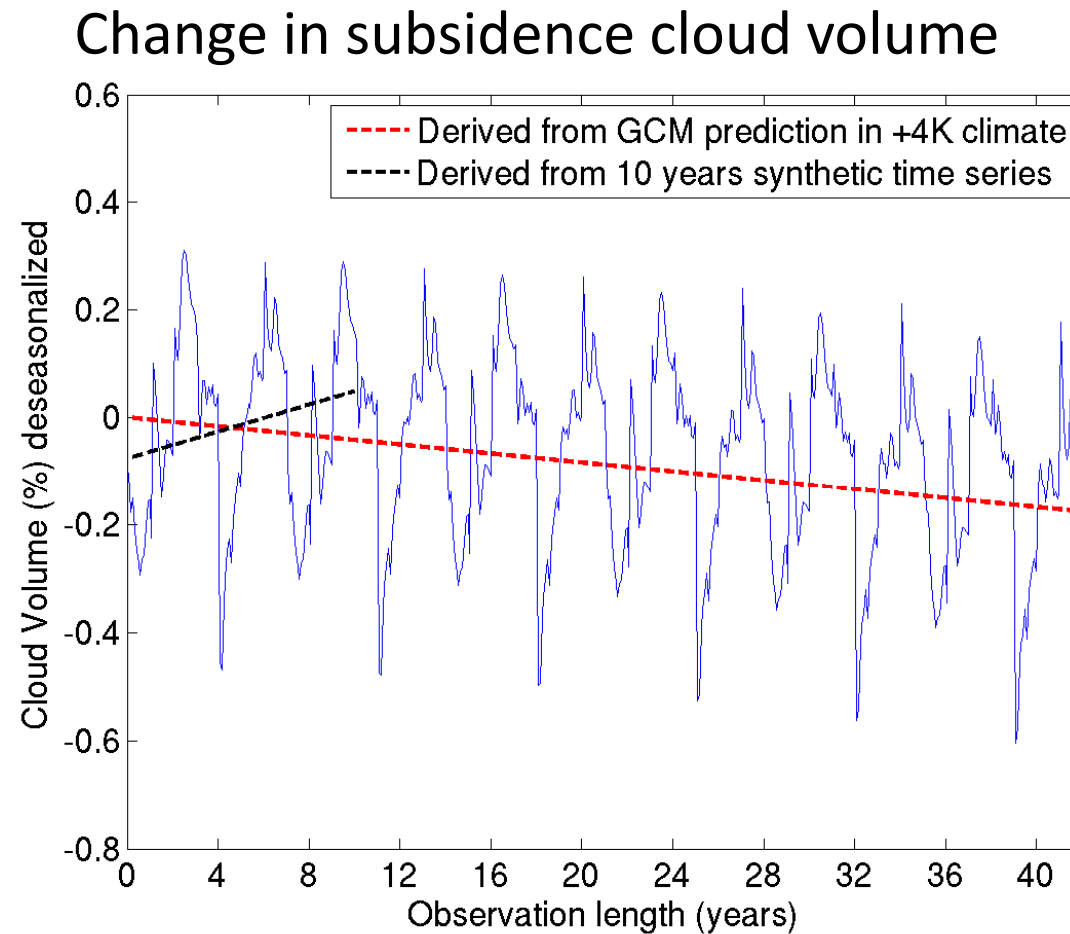
“The cloud volume” = the volume of the boundary layer (0-4km) filled with cloud

The cloud volume contains the 3D cloud information contrarily to the cloud cover or the cloud vertical profile





# About the detectability of a forced cloud volume change in the tropical subsidence using lidars



# About the detectability of a forced cloud volume change in the tropical subsidence using lidars

When no shift, no gap between successive lidar missions (ideal)

